

KABARAK



UNIVERSITY

UNIVERSITY EXAMINATIONS

2010/2011 ACADEMIC YEAR

FOR THE DEGREE OF BACHELOR OF EDUCATION

SCIENCE

COURSE CODE: COMP 327

COURSE TITLE: APPLIED NUMERICAL METHODS

STREAM: Y3S2

DAY: TUESDAY

TIME: 9.00 – 11.00 P.M

DATE: 14/12/2010

INSTRUCTIONS:

- 1. This question paper has FOUR questions**
- 2. QUESTION ONE IS COMPULSORY AND HAS 30 MARKS**
- 3. Answer any other TWO questions worth 20 marks each.**

PLEASE TURNOVER

QUESTION ONE (30 marks)

- (a) Write a program to calculate the following expression $\sqrt{(1/1+x^2)}$ (4mks)
- (b) What is the use of tolerance value in computing a problem iteratively (2mks)
- (c) How does truncation error occur? Give two examples (3mks)
- (d) State the three steps of determining the eigenvalues and eigenvectors (3mks)
- (e) With the use of an example explain predominantly diagonal system (3mks)
- (f) What is the difference between accuracy and precision (2mks)
- (g) Write an algorithm for solving a problem in Gauss Jordan method (5mks)
- (h) Write a program to solve root of a number using Newton Raphson method (6mks)
- (i) Write the predictor and corrector equation used in Euler's method (2mks)

QUESTION TWO (20 marks)

- (a) Define dominant eigenvalues and dominant eigenvectors (2mks)
- (b) Write the formula for Regular falsi method and use it to find $\sqrt{5}$ given interval [2, 3] (6mks)
- (c) Write an algorithm for Gauss elimination method (4mks)
- (d) Explain transpose of matrix with example (2mks)
- (e) How do you set convergence criterion of Gauss Seidel Method (2mks)
- (f) Define following terms giving examples in each
 - (i) Relative Error
 - (ii) Absolute error(4mks)

QUESTION THREE (20 marks)

- (a) What is an error? Explain two sources of error with examples (5mks)
- (b) Find the positive roots of the equation $x^2-2=0$ using Newton Raphson method. Start with $x_0=6$. Carry out five iterations (6mks)
- (c) Name three examples of methods used to solve linear algebra in equation and indicate whether they are direct or iterative. (3mks)
- (d) Determine the coefficient matrix, augmented matrix and solution matrix using example of three equations of three unknowns (3mks)
- (e) What are the basic assumptions behind the method of least squares? Explain (3mks)

QUESTION FOUR (20 marks)

(a) What is the meaning of nonlinear algebraic equation? **(2mks)**

(b) Find the eigenvalues and eigenvectors of the following 2x2 matrix

$$\begin{pmatrix} 8 & -4 \\ 2 & 2 \end{pmatrix}$$

(6mks)

(c) Derive the sigma notation of Taylor series

(3mks)

(d) Explain the difference between ordinary differential equation and partial differential equation

(2mks)

(e) What is the difference between Secant method and Newton Raphson method **(2mks)**

(f) Given the following set of points, obtain the table of divided difference. Use the table to estimate the value of $f(1.5)$ **(5mks)**

X_i	1	2	3	4	5
$f(x_i)$	0	7	26	63	124